Extending the Remote procedure call API

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  - disable the in game C AI
  - return True/False if successful
  - (completed)

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Implementing these two function calls

- we need to modify the Python remote procedure call interface
- then we need to modify the ioquake source code
  - (completed)

Disable/Enable ioquake AI

- this has been completed in your source file
  - these notes show how the changes were made and
  - importantly also show you which files were altered

Python

- open up `ioquake-latest/python-bot/bot-legoman/botfiles/bots/botlib.py`
- alter
-

```
# AI codes
SKILL, CONT = range(1, 3)
```


Python

- to
-

```
# AI codes
SKILL, CONT, CAI = range(1, 4)
```

- we now are going to define this new function `CAI`

Python

- now move to the definition of `class bot:` and continue down to find `def cont (self):`
- we now add
-

```
def cai (self, boolean):
    """ enables/disables the C AI engine inside ioquake "
    """ It returns the previous value of the C AI engine
    """ True means it was on, False means it was off """
    return calliB(AI, CAI, boolean)
```

Python

- `calliB` passes the three parameters as integers and returns a boolean result
- we now implement two more Python functions:
- ```
def disableAI ():
   """ disable the C AI and return True if successful """
   return cai(False)=True

def enableAI ():
   """ enable the C AI and return True if successful """
   return cai(True)=False
```
- the Python code is complete!



# C

- open up the file: `ioquake-latest/ioquake3/code/botlib/be_ai_char.c`
- ```
//a bot character
typedef struct bot_character_s
{
  char filename[MAX_QPATH];
  float skill;
  int isPythonBot;
  py_bot_t py;
  bot_characteristic_t c[1];
} bot_character_t;
```


C

- and change it to:
- ```
//a bot character
typedef struct bot_character_s
{
  char filename[MAX_QPATH];
  float skill;
  int isPythonBot;
  int c_ai;
  py_bot_t py;
  bot_characteristic_t c[1];
} bot_character_t;
```



# C

- change:
- ```
#if 1
 if ((strlen(charfile)>3) && (strcmp(&charfile[strlen(cha
   ch->isPythonBot = qtrue;
   if (initPy(&ch->py, ch)) {
     ch->skill = skill;
```

C

- to

```
#if 1
 ch->c_ai = qtrue;
 if ((strlen(charfile)>3) && (strcmp(&charfile[strlen(cha
   ch->isPythonBot = qtrue;
   if (initPy(&ch->py, ch)) {
     ch->skill = skill;
```


C

- add the new function underneath `contrpc`

C

```
/*
 *  cairpc - called by the rpc.
 *           Bytes:  <length><CODE><FUNCTION>
 *           Integer:  <True/False>
 *
 *           The Integer value turns the C AI on/off.
 */

int cairpc (void *p)
{
  py_bot_t *py = (py_bot_t *)p;
  int *onoff = (int *)&py->inBuf[3];
  bot_character_t *ch = py->ch;
  int oldValue = ch->c_ai;

  ch->c_ai = *onoff;
  returnBoolean(p, (unsigned char)oldValue);
  return qtrue;
}
```


C

- open up `ioquake-latest/ioquake3/code/botlib/be_ai_char.h` and add this prototype to the end of the file:

```
/*
 *  use_c_ai - returns true if, client, should use the C
 */

int use_c_ai (int character);
```

C

- now open up `ioquake-latest/ioquake3/code/botlib/be_ai_char.c` and add this function after `isPythonBot`

```
/*
 *  use_c_ai - returns true if, client, should use the C
 */

int use_c_ai (int character)
{
  return (botcharacters[character] != NULL) && (botcharac
}
```


C

- now we need to add the C AI rpc call, so open up `ioquake-latest/ioquake3/code/botlib/be_ai_py.h` and alter

```
/*
 *  AI codes
 */

typedef enum AIcode_t {
  pyAIDummy, pySKILL, pyCONT, pyAImax,
} AIcode;
```


C

- to

```
/*
 *  AI codes
 */

typedef enum AIcode_t {
  pyAIDummy, pySKILL, pyCONT, pyCAI, pyAImax,
} AIcode;
```


C

- alter the prototype for function `initAImethods` to

```
/*
 *  initAImethods - initialise the AI methods called by t
 */

EXTERN void initAImethods (py_bot_t *py,
                int (*skill)(void *),
                int (*cont)(void *),
                int (*cai)(void *));
```

C

- now we need to modify the call to `initAImethods` (found in file `be_ai_char.c`)
- ```
  if (initPy(&ch->py, ch)) {
    ch->skill = skill;
    initAImethods(&ch->py, skillrpc, contrpc, cairpc);
  ```


Exercise for the reader

- at this point the Python rpc mechanism can turn off/on the c_ai value
- the C ioquake code can use the function `use_c_ai` to test this bit
- we still need to modify ioquake so that it does not call the C AI if this function returns TRUE
  ```