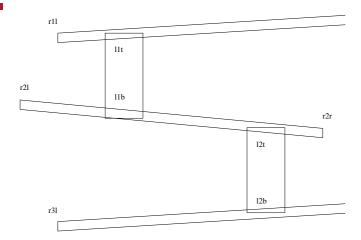
#### Python Pygame: Mario movement



#### Python Pygame: Mario movement

- Mario requires the movement
  - along ramps
  - up ladders
  - up to next ramp and down to lower ramp, when he reaches the end
- ideally he should be able to jump off ladders!
  - left as an exercise for the reader
- Mario also needs the ability to jump
  - left as an exercise for the reader

#### Python Pygame: Mario movement

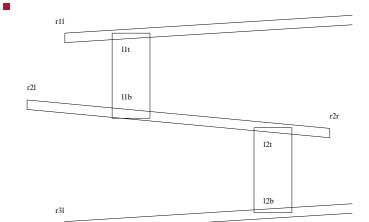
- one solution is to put Mario on rails
  - he can change direction (or path at the end of the current path)
  - he can reverse direction at any time
  - he needs the ability to choose a ladder
- placing Mario on rails is just one solution
  - another might be to use sprites for ramps and ladders and detect collisions

#### Mario on rails

- in Computer Science we often have the tradeoff between complex data structures or complex code
- adding a little complexity to the data structures will reduce the complexity of the code
- define a map for Mario, map is a dictionary of paths
  - at each end point in the Mario diagram we have a path for any chosen direction

#### Mario on rails

#### Mario on rails



- starting at r31 we note:
  - he cannot move up
  - he can move right towards r3r he will pass ladder 12b
  - he cannot move down
  - if he moves left he dies

#### where

- pointname-0 is up, pointname-1 is right,
  etc
- if the path exists it is a list

slide 7 gaius

#### Mario on rails

#### Path list

- when he reaches r3r his choices are:
  - up to ramp 2
  - back to r31
- he cannot go down and he cannot go right
- "r3r-0": ["r2r", []], # up
  "r3r-1": None, # right
  "r3r-2": None, # down
  "r3r-3": ["r31", ["12b"]], # left

- all path lists must be entered into the dictionary map
  - however is a path is not an option for Mario then its value in the dictionary is None
- any non None path will consist of the following entries:
  - first element is the furthest destination way point
  - the second element is also a list of optional ladders

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slide 11

#### Consider paths for ramp 2

## "r2r-0": None, # up "r2r-1": None, # right "r2r-2": ["r3r", []], # down "r2r-3": ["r21", ["12t", "11b"]], # left

- he cannot go up or right from point r2r
  - he can go down to r3r
  - and he can move left to r21 and optionally chose ladders 12t or 11b

### Consider paths for ramp 2

and if he reaches point r21

```
"r21-0": ["r11", []], # up
"r21-1": ["r2r", ["12t", "11b"]], # right
"r21-2": None, # down
"r21-3": None, # left
```

- here at point r21 he can move
  - up to r11
  - right (and return) to r2r possibly chosing ladders 12t and 11b
- he cannot go left or down

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## Code changes to get basic movement working

global variables initialised

#### Mario sprite class

```
class mario (pygame.sprite.Sprite):
    image = None
         _init__ (self, o, d, startpos, path):
        pygame.sprite.Sprite.__init__(self)
mario.image = pygame.image.load (barrel_colour())
        self.images = []
        self.orientation = o
        for i in mario_actions:
            self.images += [pygame.image.load (action_ima
        self.image_height = 0
        self.image\_width = 0
        self._change (d)
        self.rect = self.image.get_rect()
        self.newpath = path
        startpos = self.adjust (startpos)
        self.route = bres.walk_along (startpos, startpos)
        self.curpos = self.route.get_next ()
        self.rect.topleft = self.curpos
        self.next_update_time = 0
        self.Xspeed = 0
        self.direction = None
        self.path = None
        self.pathname = None
```

#### Mario sprite class

#### Mario sprite class

```
def new_goal (self, d):
    print "new_goal says our newpath is", self.
    self.pathname = "%s-%d" % (self.newpath, d)
    print "Mario is using path", self.pathname,
    path = map[self.pathname]
    print " = ", path
    if path == None:
        print "no path to walk along"
        self.route = bres.walk_along (self.curpos, selese:
        print "newpath = ", self.newpath
        self.path = self.newpath
        self.newpath = path[0]
        print "path = ", self.path, "newpath = ", self.lendpos = self.adjust (points[self.newpath])
        self.route = bres.walk_along (self.curpos, ender self.direction = d)
```

```
def on_ladder (self):
    if self.pathname != None:
        path = map[self.pathname]
        if path != None:
for l in path[1]:
                print 1
                 if self.is_on (points[1][0]):
                     return True, 1
    return False, self.newpath
def go (self, k):
    if k == K_RIGHT:
        self._horizontal (1, stand_right)
    elif k == K_LEFT:
        self._horizontal (3, stand_left)
    elif k == K_UP:
        self._vertical (0, up_right)
    elif k == K_DOWN:
        self._vertical (2, up_left)
```

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#### Mario sprite class

#### Mario sprite class

```
_horizontal (self, newdir,
if self.direction in [0, 2]:
     # could be going up a ladder or between ramps
     if self.route.finished ():
         # we have reached the end of the ladder of
         self.orientation = o
         self._change (o)
         self.next_update_time = 0
         self.new_goal (newdir)
else:
     if self.direction == newdir:
         # same direction, just continue, faster
self.Xspeed = min (self.Xspeed + step_hor
         self.orientation = o
         self._change (o)
         self.next\_update\_time = 0
         self.new_goal (newdir)
```

```
_vertical (self, newdir, o):
if self.direction in [1, 3]:
    # going left or right, check if we can use la
    b, self.newpath = self.on_ladder ()
    if b:
        print "using a ladder", self.newpath
        self.orientation = o
        self._change (o)
        self.next_update_time = 0
        self.new_goal (newdir)
    elif self.route.finished ():
        # can also go up at the end of the ramp
        self.orientation = o
        self._change (o)
        self.next_update_time = 0
        self.new_goal (newdir)
```

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slide 20 gaius

#### Mario sprite class

#### Mario sprite class

```
else:
    # already going up or down, might be on a ladd if self.direction == newdir:
    # same direction, just continue, faster self.Xspeed = min (self.Xspeed + step_verelse:
    # change of direction self.orientation = o self.orientation = o self.change (o) self.next_update_time = 0
    # check to see if already on ladder if (self.pathname != None) and (self.pathname with make new goal the previous start self.newpath = self.pathname self.new_goal (newdir)
    else:
        self.new_goal (newdir)
```

```
def _change (self, d):
    self.image = self.images[d]
    self.image_height = mario.image.get_height()
self.image_width = mario.image.get_width()
    self.next_update_time = 0
def update (self, current_time):
    if self.next_update_time < current_time:</pre>
        if self.Xspeed > 0:
             self.curpos = self.route.get_next
             self.rect.topleft = self.curpos
             self.Xspeed -= 1
             self.next_update_time = current_time + 1
def adjust (self, p):
    return [p[0], p[1]-self.image_height]
def is_on (self, x):
    return not ((self.curpos[0] + self.image_width <
                 (self.curpos[0] > x + xpos (ladder_wi
```

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#### <u>Mario sprite class</u>

#### Mario sprite class

```
def checkInput():
    for event in pygame.event.get():
        if event.type == KEYDOWN:
        if event.key == K_ESCAPE:
            sys.exit (0)
        elif event.key in [K_RIGHT, K_LEFT, K_UP,
            M.go (event.key)
        elif event.key == K_f:
            pygame.display.toggle_fullscreen()
```

```
def play_game (screen):
    global M
    0 = -1
    M = mario (stand_right, 1, points["r31"], "r31")
    while True:
        t = pygame.time.get_ticks()
        if o != t:
            activity_scheduler (t)
            o = t
        checkInput()
        screen.fill(white) # blank the screen.
        draw_polygons ()
        for b in barrels:
            b.update (t)
            screen.blit (b.image, b.rect)
        M.update (t)
screen.blit (M.image, M.rect)
        pygame.display.flip ()
```

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#### Homework and tutorial

- finish the path map definition and integrate the movement into your code
- make Mario jump, fall off ladders
- improve speed of movement and smoothness/playability
- scoring, timing, sounds etc

#### PGE input

- implementing Mario using the Physics game engine is much easier!
- since the ball representing Mario is free running it just needs to be given a push when we want it to move
- we could
  - push it left with the left mouse button
  - push it right with the right mouse button
  - up with the middle mouse button

#### PGE input

# def mouse\_hit (e): global m mouse = pge.pyg\_to\_unit\_coord (e.pos) if e.button == 1: m.put\_xvel (gb.get\_xvel ()-0.3) elif e.button == 3: m.put\_xvel (gb.get\_xvel ()+0.3) elif gb.moving\_towards (mouse[0], mouse[1]): pos = m.get\_unit\_coord () # print "mouse =", mouse, "ball =", pos m.apply\_impulse (pge.sub\_coord (mouse, pos), 0.4) else: m.put\_yvel (m.get\_yvel ()+0.4)

#### PGE input

- in the main function we register the mouse event with our function
- pge.register\_handler (mouse\_hit, [MOUSEBUTTONDOWN])
- please see the implementation of breakout to see how this is integrated into a game breakout example ⟨http://floppsie.comp.glam.ac.uk/ Glamorgan/gaius/pge/homepage.html⟩

slide 24

#### Collisions in PGE

- notice that the section of code containing delete\_me and box\_of

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#### **Collisions in PGE**

- the function box\_of creates a blue box at pos with a width and height
- it also stipulates that this box is fixed
- furthermore if anything hit this box then the function delete\_me is called

#### Collisions in PGE

```
def delete_me (o, e):
    global blocks, winner, loser

    blocks.remove (o)
    o.rm ()
    if blocks == []:
        if not loser:
            winner = True
            pge.text (0.2, 0.3, "Winner", white, 100, 1)
            pge.at_time (4.0, finish_game)

def box_of (pos, width, height, color):
    global blocks

blocks += [pge.box (pos[0], pos[1], width, height, co.fix ().on_collision (delete_me)]
```

slide 28

#### **Collisions in PGE**

- the function delete\_me is a call back registered by the call to on\_collision (described on the previous slide)
- this call back must be defined taking two parameters
  - the first, o, is the object whose callback is being called
  - the second, e, is the collision event which has describes the collision
- by using the event, e, it is possible to find out the other object in collision and other properties (if necessary)