

## Embedded systems

- there are many times an IBM-PC is an overkill solution
- an IBM-PC is a general purpose computer, sometimes a more specific computer is cost effective
- a specific computer executing a specific operating system might be the solution and in a minimal case we might choose to use an embedded operating system
  - or embedded system if we include the application

## Characteristics of an embedded system

- these systems can be tiny
  - could be < 1KBytes
- only use software which you need
  - for example many times it is possible to implement an embedded system using no interrupts
  - choice, it might be
    - easier to implement
    - guarantee a hard realtime performance for time critical applications

## Case examples: embedded systems built using the ATmega328p

- we will look at building a basic computer running a tiny embedded system
  - flashing LED program
- many, many other examples in which the ATmega328p can be used
  - network on/off switch
  - cruise controller for an electric bicycle
  - amplifier controller
  - tiny web server and LCD panel
  - Arduino!

## Why use ATmega processors?

- support within gcc is mature (it has support ATmega microprocessors for about two decades)
  - the ATmega series of microprocessors have very similar instructions
- harvard risc architecture

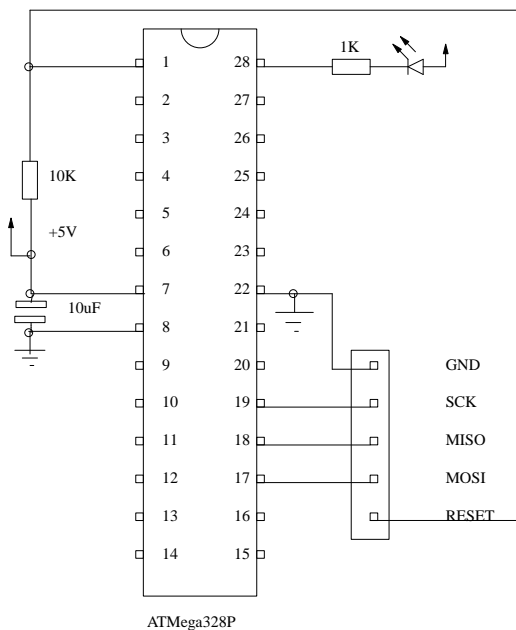
## Atmel ATMega series of microprocessors

- the number of components to make a minimal system is tiny
- they are also extremely easy to interface to peripherals
  - A->D, D->A, pwm (servo and motor control) etc
  - multiple hardware timers etc

## Atmel 328p

- is an 8-bit AVR RISC-based microcontroller (some of its features include):
  - 32KB flash memory
  - 1024B EEPROM, 2KB SRAM
- 23 general purpose I/O lines
  - 32 general purpose working registers
  - three flexible timer/counters with compare modes
  - internal/external interrupts, a 6-channel 10-bit A/D converter
  - programmable watchdog timer with internal oscillator
  - 2 PWM channels (ie control two servos) in hardware
- many features omitted for sake of brevity

## Simple computer flashing a LED with the ATMega328p



## Code for the flashing LED

```

MODULE flashed ;

PROCEDURE Turn (on: BOOLEAN) ;
BEGIN
  IF on
  THEN
    (* turn LED on *)
    ASM VOLATILE ("cbi 8,5");
  ELSE
    (* turn LED off *)
    ASM VOLATILE ("sbi 8,5");
  END
END Turn ;

(*
  InitLed - initialize pin 0 as an output
*)

PROCEDURE InitLed ;
BEGIN
  ASM VOLATILE ("sbi 7,5")
END InitLed ;

```

## Code for the flashing LED

```

CONST
    Delay = 400 ;

VAR
    i, j: CARDINAL ;

```

## Code for the flashing LED

```

BEGIN
    InitLed ;
    Turn(FALSE) ;
    LOOP
        FOR i := 0 TO Delay DO
            FOR j := 0 TO Delay DO
                ASM VOLATILE ("nop")
            END
        END ;
        Turn(TRUE) ;
        FOR i := 0 TO Delay DO
            FOR j := 0 TO Delay DO
                ASM VOLATILE ("nop")
            END
        END ;
        Turn(FALSE)
    END
END flashed.

```

## Cruise controller for an electric bicycle

- uses PWM device to control the power delivered to the electric motor
- uses a A to D device to take input from the throttle (potentiometer)
- uses several output pins to control status LEDs
- uses input pins for wheel movement sensing
- due to the hardware support inside the Atmega328p the software is extremely simple
  - no need for interrupt service routines
  - no need for separate processes

## Amplifier control embedded system

- uses the Atmega328p to
  - turn on the +-12v power
  - turn on the +-9v power
  - connect the speakers after 2 seconds (speaker protection)
  - uses the A to D device to take input from a potentiometer to select input source

## Amplifier control embedded system

- uses input lines to detect push button
  - three pulses turns it off
  - two pulses turns off the speakers
  - one pulse resets the power save timer
  
- software is a simple C program which controls hardware directly

## Conclusion

- embedded systems come in many sizes and the examples given here are tiny applications
  
- embedded systems might range up to and including the Linux kernel (with various scheduling and device driver changes)